Commentary: Pushing the limits: Robotic mitral valve surgery in cardiac dextroversion

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We commend Bourdillon and colleagues on this case, which details the successful treatment of mitral regurgitation in a patient with cardiac dextroversion. We believe this report offers valuable insight into not only the recovery advantages of a robotic approach but also its ability to treat complex cardiac surgical pathologies that have traditionally required open intervention.

The approach to mitral valve repair has significantly evolved within the past several decades. Initial attempts at modern repair were influenced by Dr Alain Carpentier in 1983, when he discussed mitral valve disease and the steps needed for safe and effective reconstruction. The approach to exposure at this time and for many subsequent years after was through median sternotomy, which allows for direct visualization and exposure to the entire heart and vessels. Dr Carpentier and his team reported favorable outcomes through open sternotomy, with strong freedom from cardiac-related morbidity and mortality in addition to low rates of reoperation.

In recent years, surgeons have turned to less invasive alternatives, including minimally invasive mitral valve surgery (MIMVS) and robotic surgery to avoid open sternotomy while continuing to provide high quality results. MIMVS typically refers to operating through a right-sided minithoracotomy or ministernotomy. Robotic assistance is added by some to the minithoracotomy. Totally endoscopic robotic mitral valve surgery is performed with a robotically controlled endoscope and wristed remotely controlled instruments and an 8 to 30 mm working port without any rib spreading, an even less invasive approach than MIMVS. There are data to support shorter hospital stay lengths and noninferior postoperative outcomes in patients undergoing robotic versus normal repair. With an experienced team, robotic surgery can lead to a successful hospital course after mitral valve surgery without the need to open the chest.

Successful mitral valve repair in patients with dextroversion requires a complete understanding of the anatomic variations, such as the positioning of the pulmonary trunk relative to the aorta discussed by the authors. Furthermore, patients with dextroversion and situs solitus may also present with additional technical challenges such as univentricular systems and atrioventricular discordance. Its very interesting to see that the mitral valve is upside down compared with normal anatomy.

We would like to specifically highlight the adaptability of robotic port placement demonstrated by this case. At our center, ports for robotic mitral valve repair are typically placed on the patient’s right side in approximately the third through seventh intercostal spaces in the right axilla to facilitate access to left atrium. However, the dextrocardia present in the authors’ patient required port placement on the patient’s left side, reversing the typical robotic approach to access the patient’s reversed cardiac anatomy. Although

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cardiac dextroversion is quite rare, with an estimated incidence of approximately 1 in 12,000 pregnancies, this case highlights the broader adaptability of robotic cardiac surgery, which allows the operative approach to be tailored to each patient’s unique technical challenges.

The ultimate goal for surgical interventions beyond safety and efficacy is to minimize invasiveness and thus maximize patient satisfaction. As evidenced by the authors’ successful completion of a complex robotic mitral valve repair in a patient with cardiac dextroversion, robotic cardiac surgery is a dynamic tool capable of achieving this goal. With adequate investment in the requisite equipment and personnel training, we believe the robotic approach offers a safe and effective means to usher in an era of minimally invasive cardiac surgery for the treatment of complicated pathologies that have traditionally required open surgery.

References